SCHEME OF COURSE WORK

Course Title	COMPUTER AIDED MANUFACTURING AND ROBOTICS LAB						
Course Code	19ME2108 L P C 0 3 1.5						
Program:	M.Tech.						
Specialization:	CAD/CAM						
Semester	П						

Course Outcomes (COs):

At the end of the course, the student will be able to

1	Create the part model and simulate drilling operations using CAM software.
2	Generate the tool path and NC part program for milling and turning operations using CAM software.
3	Demonstrate facing, turning and threading operations on CNC lathe.
4	Demonstrate drilling and contouring operations on PKM.
5	Develop programs on robotic arms.

Program Outcomes (POs)

At the end of the program, the students in CAD/CAM will be able to

- 1. acquire fundamentals in the areas of computer aided design and manufacturing
- 2. apply innovative skills and analyze computer aided design and manufacturing problems critically
- 3. identify, formulate and solve design and manufacturing problems
- 4. carry out research related to design and manufacturing
- 5. use existing and recent CAD/CAM software
- 6. collaborate with educational institutions, industry and R&D organizations inmultidisciplinary teams
- 7. apply project and finance management principles in engineering projects
- 8. prepare technical reports and communicate effectively
- 9. engage in independent and life-long learning and pursue professional practice in their specialized areas of CAD/CAM
- 10. exhibit accountability to society while adhering to ethical practices
- 11. act independently and take corrective measures where necessary

Course Outcome versus Program Outcomes:

COs	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12
CO-1	S	S	M	M	S				M			
CO-2	S	M	M	M	S				M			
CO-3	M	M	M						M			
CO-4	M	M	M	M					M			
CO-5	M	M	M	M					M			

- S Strongly correlated, M Moderately correlated, Blank No correlation
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Teaching-Learning and Evaluation

WEEK	TOPIC / CONTENTS	COU	SAMPLE VIVA QUESTIONS	TEACHI	ASSESSME
		RSE	2011011	NG-	NT
		OUT COM		LEARNI NG	METHOD &
		ES		STRATE	SCHEDUL
1		CO1	Explain the various commands available in CAM	GY Explainin	Е
1	Creating a 2D part	COI	software for creating 2D profile.	g various	
	model using CAM software		2. Describe the procedure for simulating the drilling operation.	commands and	
2	Tool path simulation	CO1	3. What is the meaning of G81 and G80 NC code?	simulation	
	and NC code generation	COI		of CNC operations	
	for drilling operations			using	
	using CAM software			CAM software	
2	m 1 1 1 1 1 1	COA	4 Wh	Software	
3	Tool path simulation and NC code generation	CO2	1. What are the various operations which can be performed in CNC lathe?		
	for milling operations		2. Explain the criteria for selecting the particular tools in CNC milling.		
	using CAM software		3. What is the code for rough turning cycle and		
			finishing cycle?		
4	Tool path simulation	CO2			
	and NC code				
	generation for turning operations using CAM				Day to day
	software				experiments,
5	Mode selection and tool	CO3	 Explain Edit mode and MDI mode. G00, G01 and G02 code is used for 	Demonstr ation on	Record
	offsetting on CNC lathe		3. M03, M05 and M30 code means	CNC lathe	
6	CNC nest macrom for	CO3		for facing and	
0	CNC part program for facing and step turning	CO3		turning	
	on CNC lathe machine			operations	
7	CNC part program for	CO3			
,	taper and circular	003			
	turning on CNC lathe				
	machine				
8	Backlog Experiment/ Revision/ Practice	CO1,			
	KCVISION/FIACUCE	CO2, CO3			
9	Mid-Test 1	CO-1,			Internal Exam-1
		CO-2,			& Viva voce
		CO3			

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10	CNC part program for threading on CNC lathe machine	CO3	What is the syntax for threading operation on CNC lathe?	Demonstra tion on CNC lathe for threading operation.	
11	CNC part program on milling machine		Explain the working principle of 3D printing. Explain the various applications of PKM machine. Define degree of freedom.	Demonstr ation on CNC milling, 3D printing and PKM machine	
12	Design and build a simple solid model using 3D printing	CO4			Day to day experiments,
13	Drilling on 2-DOF PKM	CO4			Record
14	Contouring on 3-DOF PKM	CO4			
15	Programming on 4- DOF SCARA robot	CO5	 Differentiate between SCARA robot and Articulated robot. Write a program to move the objects from one place to another place. 	Demonstr ation on 4-DOF SCARA robot and 6-DOF Articulat ed robot	
16	Programming on 6- DOF Articulated robot	CO5			
17	Backlog Experiment/ Revision/ Practice	CO3, CO4, CO5			
18	Mid-Test 2	CO-3, CO- 4, CO-5			Internal Exam-2 & Viva voce

19/20	END EXAM	All		Experiments
		Cos		& Viva
				voce